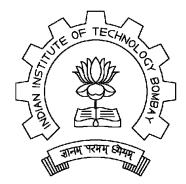
Embedded Systems (Software)

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Embedded System Diversity

Beware of the computer!



- From computers to embedded & networked SoCs ... IoT
- Complete change in device interaction
- Growing number of critical applications

Common Design Metrics

- NRE (Non-recurring engineering) cost
- Unit cost
- Size (bytes, gates)
- Performance (execution time)
- Power (more power=> more heat & less battery time)
- Flexibility (ability to change functionality)
- Time to prototype
- Time to market
- Maintainability
- Correctness
- Safety (probability that system won't cause harm)

Apple "A" series SoC

- Apple A4 (2010)
 - for iPad ARM based SoC @1GHz w/integ. GPU (\$1Bn to devlp)
- Apple A5 (2012)
 - Based on dual-core ARM Cortex-A9 MPCore CPU
 - \$4B development facility by Samsung in Texas
 - Clocked at 1 GHz (auto adj. frequency to save battery)
 - ISP for face detection, wh.balance & automatic image stabilization
 - "EarSmart" unit from Audience for noise canceling
 - CPU portion 2x as powerful as the original iPad
 - GPU up to 7x as powerful A4
 - Cost 75% more than predecessor
- Apple A6x (2013)
 - 1.4 GHz Apple-designed <u>ARMv7</u> based <u>dual-core CPU</u> (Swift)
 - Integrated quad-core <u>PowerVR</u> SGX 554MP4 GPU @300 MHz
 - 2x computing power + graphics perf. of previous <u>Apple A5X</u>
 - 32 nm process => chip is 123 mm² large^[6] (26% larger than A6).

(Apple) Processor Trends

Year	Model	Specs	Produ ct	Spd	Gfx	Size	Tech.
		1.3 GHz ARMv7 based					
2012	46	dual-core CPU (Swift)	iPhone5	2x	2x	22% smaller	32nM
2013	47	1.3–1.4GHz 64-bit ARMv8-A dual-core CPU (Cyclone) integrated PowerVR G6430 GPU, 31x64bit GP regs, 32x128bit FP regs	iPhone 5S, iPad Mini2 & 3	2x	2x	1B transistors in 102sq.mm	28nM
2014 /	48	1.4GHz 64-bit ARMv8-A dual-core CPU & integrated PowerVR GX6450 GPU	iPhone6 & 6+	25%	50%	13% less in size, 2B transistors 89sq.mm	20nM
		64-bit ARM based system	iPhone 6S &	70%	90%		
2015	49	on a chip (SoC)	6S+	more	more		14nM

(Apple) Processor Trends

Year	Model	Specs	Product	Spd	Gfx	Size	Tech.
2017	A11	64-bit ARMv8-A 6-core CPU (Bionic) 2 high perf and 4 high efficiency	iPhone 8	25% faster	70% faster	4.3B transistors	10nM
2018	A17	64-bit ARM 2+4 core CPU (Bionic)	iPhone XS & XR	35% faster	95% faster multi	6.9B transistors	7nM
2018		64-bit ARM 6 core with 2 high perf cores running at 2.65GHz (Lightening) with ML accelerators – AMX blocks; & 4 energy efficient cores (Thunder)	iPhone 11	20% faster with 30% less pwr	20% faster with 40% lower pwr	8.5B transistors	7nM
2020 2022 A16		Apple A14 Bionic (hexa-core 64-bit ARM64 "mobile SoC", SIMD, caches) Apple A16 Bionic 6-core 64-bit ARMv8.6A SoC 6 core Neural Engine	iPhone 12 iPhone 14	40%	30% faster 50% faster	11.8B transistors 16.0B transistors	5nM 4nM

(Apple) Processor Trends

Year	Model	Specs	Product	Spd	Gfx+AI	Size	Tech.
2024	A18	Apple A18 Bionic (hexa-core 64-bit ARM64 "mobile SoC") High-perf core (4) @4.04GHz High-efficiency cores(2) @2.11GHz	iPhone 16	30% faster than A16	5-core gfx, 16-core Neural engine (AI) 35 T opn/s 40% faster than A16	19B Trans 90mm ²	ЗnМ

Challenges

.Decreasing Mission & Safety-Critical Pressures Increasing...

- Tolerance for defects
- Development Cycles
- Resource availability
- Ability to manage reqs
- Ability to ensure long term maintenance

- Safety critical requirements in
 - Aerospace & defence, Energy Transportation, Industrial, Medical
- Requirement changes, life span
- Application complexity
- Cost of code testing, validation & verification & certification
- Need for systems & software design reusability
- Packaging & ergonomics are key
- Mechatronics
- Mass deployment less scope for error

Current Technology

Extrapolation of traditional software techniques

- Programs written in conventional languages C subsets, MISRA C for automobile Java for telephone / smartcards
- Glued together by OS services
 A wide variety of embedded OS (VxWorks, OSEK)
- With some reuse and standardisation effort
- Classical software models largely inadequate
 Too powerful, hard to verify
 often subsets of rich languages=>doesn't make them simpler

Why Is Embedded Software Not Just Software On Small Computers?

- Embedded = Dedicated
- Interaction with physical processes
 - Sensors, actuators, processes
- Critical properties are not all functional
 - Real-time, fault recovery, power, security, robustness
- Heterogeneity
 - Hardware/software tradeoffs, mixed architectures
- Concurrency
 - Interaction with multiple processes
- Reactivity
 - Operating at the speed of the environment

These features look more like hardware!

Current Bottleneck

- Intrinsic application complexity grows rapidly Analog / digital interface: more objects to control Embedded algorithmics: signal, display, alarm, power... Richer hardware architecture: μP, DSP, ASIP, ASIC, FPGA
- Performance adds complexity

Footprint / power minimization interferes with logical design Technology independence is still difficult

=> Verification bottleneck

Applications hard to verify off-site Hardware / software interaction difficult

Software Engineering

(or, how do we build reliable systems?)

Things Have to Change!

- Pressure on productivity of design engineers working on complex systems.
- Time has come to design hardware using software engineering rather than hw engg methodologies.
- Complexity of system is the basic problem, and Moore's Law doubles complexity every 18 months.
- Advances in software engineering help produce complex systems with more easily available design skills, making large profits
- We expect new designers, with/without hardware design skills, will design hardware in future

Designer Productivity

- "The Mythical Man Month" by Frederick Brooks '75
- More designers on team => lower productivity because of increasing communication costs between groups
- Consider 1M transistor project:
 - Say, a designer has productivity of 5000 transistor/mth
 - Each extra designer => decrease of 100 transistor/mth productivity in group due to comm. costs
 - 1 designer 1M/5000 => 200mth
 10 designer 1M/(10*4100) => 24.3mth
 25 designer 1M/(25*2600) => 15.3mth
 - 27 designer 1M/(27*2400) => 15.4mth
- Need new design technology to shrink design gap

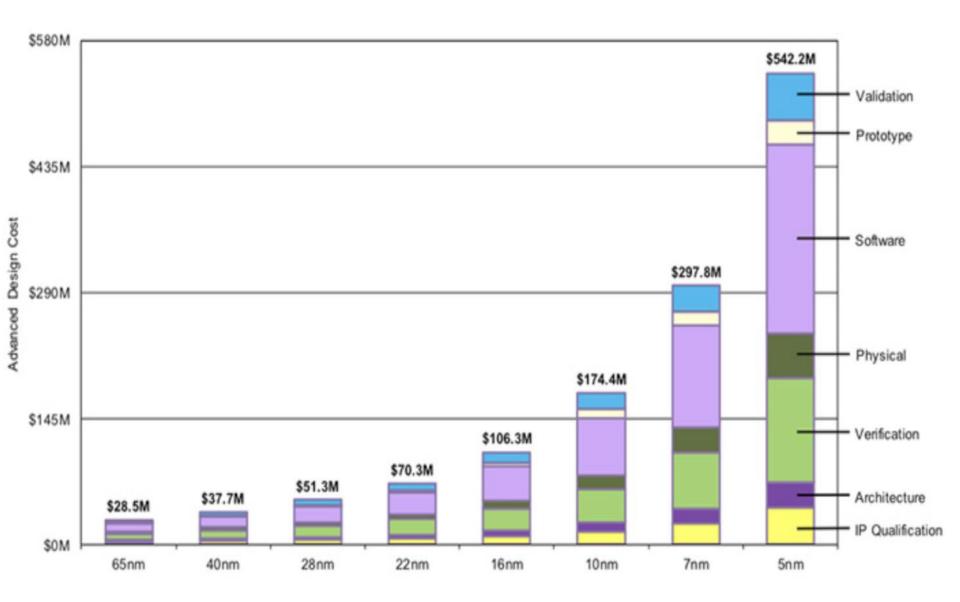
Design Productivity Gap

- Designer productivity grown over the last decade
- Rate of improvement has not kept pace with the chipcapacity growth
- 1981: leading edge chip:
 - 100 designers * 100 trans/mth => 10k trans complexity
- 2010: leading edge Intel chip using 45nM te
 - > 1B transistor complexity

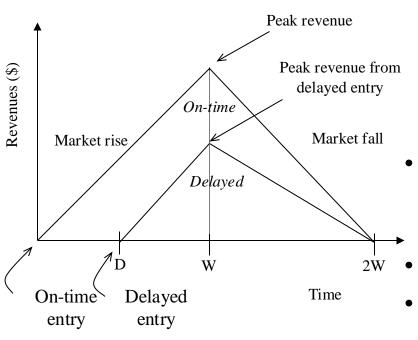


- 2015: Leading edge Apple A9 using 14nM technology:
 - > 2B transistor complexity
- 2020: Apple A14 chip using 5nM technology:
 - > 11.8B transistor complexity
- 2023: Apple A16 Bionic chip (iPhone 14) using 3nM tech:
 - > 16-20B transistor complexity
- Designers at avg. of \$10k pm
 => cost of building leading edge chips has gone from \$1M ('81)-> \$300M (2002)-> \$1B (2010)-> \$5B (2020)-> \$10B+ (2023)
- Need paradigm shift to cope with complexitie Sesign: Frank Vahid/ Tony Vargi (John Wiley & Sons, Inc. 2006) And others.

Chip Design Cost

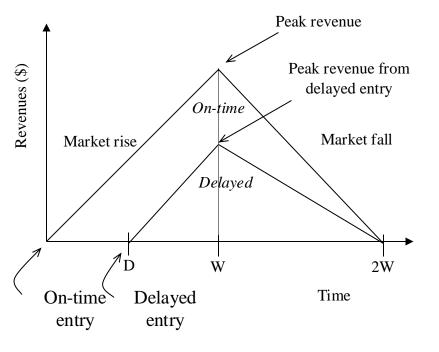


Time to Market Design Metric



- Simplified revenue model
 - Product life = 2W, peak at W
 - Time of market entry defines a triangle, representing market penetration
 - Triangle area equals revenue
 - Loss
 - The difference between the on-time and delayed triangle areas
- Avg. time to market today = 8 mth
- 1 day delay may amount to \$Ms
 - see Sony Playstation vs XBox

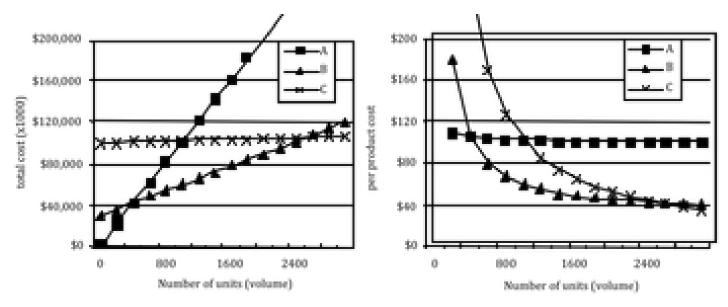
Losses due to delayed market entry



- Area = 1/2 * base * height
 - On-time = 1/2 * 2W * W
 - Delayed = 1/2 * (W-D+W)*(W-D)
- Percentage revenue loss
 = (D(3W-D)/2W²)*100%
- Try some examples
 - Lifetime 2W=52 wks, delay D=4 wks
 - $(4*(3*26-4)/2*26^2) = 22\%$
 - Lifetime 2W=52 wks, delay D=10 wks
 - $(10^{*}(3^{*}26 10)/2^{*}26^{2}) = 50\%$
 - Delays are costly!

NRE and unit cost metrics

- Compare technologies by costs -- best depends on quantity
 - Technology A: NRE=\$2,000, unit=\$100
 - Technology B: NRE=\$30,000, unit=\$30
 - Technology C: NRE=\$100,000, unit=\$2



But, must also consider time-to-market

Source: Embedded System Design: Frank Vahid/ Tony Vargis (John Wiley & Sons, Inc. 2002)

Trends (Moore's Law)

IC transistor capacity doubles every 18 mths

- 1981: leading edge chip had 10k transistors
- 2002: leading edge chip has 150M transistors
- 2010: Leading edge Intel processor has 0.5B trans in 107sq.mm
- 2014: Leading edge Intel processor has 2.0B trans in 89sq.mm
- 2019: Leading edge Intel processor has 8.5B trans in 83sq.mm
- 2022: Apple A16 processor has 16B transistors
- 2024: Apple A18 processor has 19B transistors

• Why?

- Reducing transistor size, increasing chip size, clever circuits
- Changing due to paradigm shifts: sys design tools, nanotech, ...

Trends (Designer Productivity)

• Designer productivity improved due to better tools:

- Compilation/Synthesis tools
- Libraries/IP
- Test/verification tools
- Standards
- Languages and frameworks (Handel-C, Lava, Esterel, ...)
- 1981: designer produced 100 transistors per month
- 2002: designer produces 5000 transistors per month
- 2024: designer produces 8-10M transistors per month
 - Apple A18 chip has 19B transistors
 - Extensive teamwork, wutomation w/ modern design automation (EDA) tools
 - 100 engineers over 18-24 months => 8-10M transistors/mth

Key Insights

- 1. Exponential Growth: #transistors in chips increasing exponentially
- 2. Technological Advancements: Growth driven by semiconductor tech, photolithography, materials sc., chip design methodologies.
- **3. Performance and Efficiency:** As #transistors increases, chips become more powerful and efficient, allowing more complex computations and better performance.
- 4. Cost Reduction: Increase in transistor density leads to reduction in cost per transistor
- 5. Market Impact: The growth in transistor count enables more advanced features and capabilities in devices.
- 6. Future Projections: More increases in transistor counts in coming yrs, =>further Innovations in technology & computing power."

Software Engineering... Why we need it?

Enemy number 1 : the bug

- Therac 25 : lethal irradiations
- Dharan's Patriot
- Ariane V
- Mars Explorer, Mars Polar Lander
- High-end automobile problems
- Pentium, SMP CPU networks
- Telephone and camera bugs



Bugs grow faster than Moore's law!





Other Important Issues

• Hardware / software partitioning

Hardware / software source code independence Link between programming and performance analysis

Operating Systems / scheduling

Well-studied field: rate-monotonic, earliest deadline first, etc. Newer computation models need less explicit scheduling

Fault tolerance

Software redundancy, voting algorithms, etc. CRCs, TT networks

How to avoid or control bugs?

- Traditional : better verification by fancier simulation
- Next step : better design using specific techniques
 Better and more reusable specifications
 Simpler computation models, formalisms, semantics
 Reduce architect / designer and customer / provider distance
 Reduce hardware / software distance
- Requires better tooling

Higher-level models and synthesis Formal property verification / program equivalence Certified libraries

Anatomy of Embedded Applications

- CC : continuous control, signal processing Differential equation solving, filters Specs and simulation in Matlab / Scilab, manual or automatic code
- FSM : finite state machines, state transition systems Discrete control, protocols, networking, drivers, security, etc. Flat or hierarchical state machines, manual or automatic code
- Calc : calculation intensive Navigation, security, etc.
 C, manual + libraries
- Web : web-like navigation, audio / video streaming Consumer electronics, infotainment systems Data-flow networks, embedded Java

BMW 745i : Prelude To Complexity



Another Life Cycle Example : The Software Error

External view

The problem: software error, a desynchronization of the valvetronic motors



- Rough running engine, possibly stall
- Severity: 6 incidents in 5,470 cars with 2 rear endings
 - "alleged injury" of BMW passengers
 - Fault of drunk or inattentive following drivers

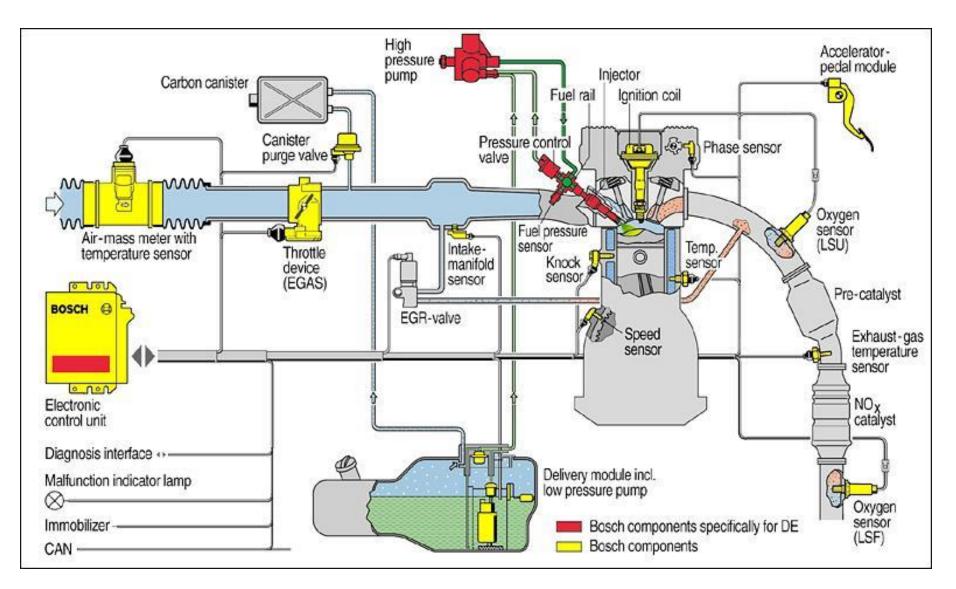
BMW Cost

- To repair: Reprogram ECU
- Recalls not uncommon in industry

 BMW 5,470 cars @ \$68,500 = Rev \$372 mil
- Compare Cost: Recall BMW X5
 - 164,000 units @ \$66,800 = Rev \$10 bil.
 - ~\$5 Million
 - -~\$30 per SUV



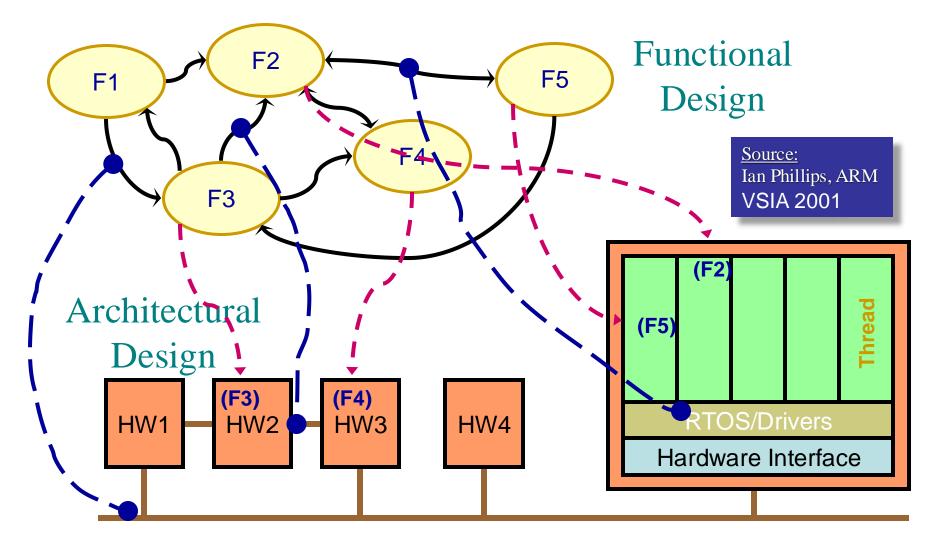
Bosch EMU For Four Wheeler (Multi Cylinder)



Design Issues

(How do we build these systems?)

Functional Design & Mapping



Synchronous languages

Started in the 80's

Esterel : Ecole des Mines / INRIA, SyncCharts : U. Nice Lustre : IMAG, Signal : INRIA Rennes Lava : Chalmers, Xilinx

Started in the mid-90's

•Handel-C: University of Oxford, Celoxica Inc.

• Industrial use in the 90's

Lustre / SCADE : nuclear plants (Schneider), avionics (Airbus) Esterel : avionics (Dassault), telecom

=> Full development in the 2000's

avionics: Airbus, Dassault, Elbit, Eurocopter, SNECMA, Thales,... automotive: AUDI, GM, PSA,...

hardware pilot projects / experiments: TI, STM, Xilinx, Intel, Thales

How do we get there?

KNOWLEDGE OR SKILLS REQUIRED

- Design of Solutions
- Investigation
- Modern Tool Usage
- Individual & Team Work
- Communication

Conclusion

- We have simultaneous optimisations of competing design metrics: speed, size, power, complexity, etc.
- Software engineering issues apply
 - Non-recurring engineering costs are critical
 - Design-productivity / time-to-market is paramount
- Traditional technologies unequipped to build complex embedded systems

- Need unified view of hardware/ software co-design.

 Design focus at higher levels of abstraction => Abstract specs refined into programs then into gates and logic